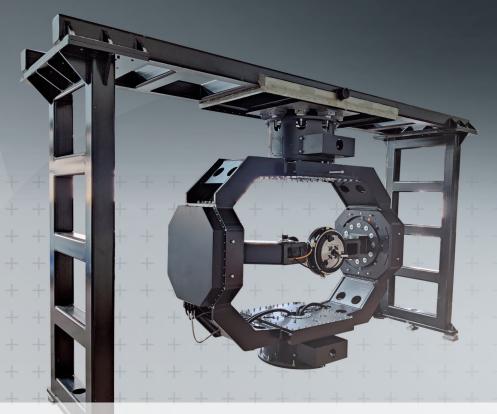


AZ/EL/ROLL / NULL SEEKER Null Seeker Positioner



AL-9301

The Null Seeker Positioner is used in development and production testing to emulate flight movement of a device encasing null-seeker sensors. Its high motion dynamics and ultra-precise angular positioning, rates, and acceleration allow for accurate evaluations of null seeker technology (ie. RF signal nulls transmitted from directive antennas).

APPLICATIONS

- Null seeker testing & calibration
- Airborne target tracking
- Electro-optical device testing
- Indoor Use

PRODUCT HIGHLIGHTS

- Fast seeker head positioner
- High dynamic performance
- High inertia/ high accuracy flight motion simulation

FEATURES

- · Large, 3-axis gimbal
- Repeated and defined motion cycles
- · Minimum clean field of view in EL angle ± 75°, AZ ± 63°
- Roll travel range ±180° or continous
- AZ and EL with zero backlash drive system
- Max. design weight 35 Kg with reduced perfor-
- Accomodates large antennas (up to 25 kg)
- Limit switches and brakes to end AZ and EL movements
- Internal roll thru-hole diameter 230 mm

Specifications – Null Seeker Positioner

PARAMETER UNITS	MODEL
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		Dimensional Drawing Number	ICD	DCD221-0567
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OPERATIONAL

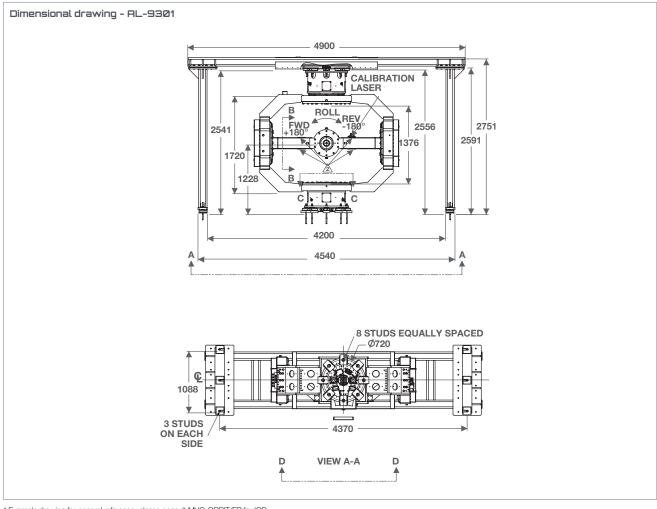
	YAW		± 63
Travel Range	PITCH	Deg	± 75
	ROLL		± 180 ¹
	YAW		60
Speed	PITCH	Deg/Sec	60
	ROLL		170
	YAW		170
Acceleration	PITCH	Deg/Sec ²	170
	ROLL		340
	YAW		0.0007
Position Resolution	PITCH	Deg	0.0007
	ROLL		0.0007
	YAW	Deg	0.003
Repeatability ²	PITCH		0.003
	ROLL		0.003
	YAW		200
Stabilization Time	PITCH	msec	200
	ROLL		200
	YAW		1000
Position Data Rate	PITCH	Hz	1000
	ROLL		1000

PHYSICAL

Height	in	108.3
	mm	2751
Waight	lbs	8818
Weight	kg	4000
DUT Interface Plate Diameter	in	11.97
	mm	304

ENVIRONMENTAL

Operating temperature	21° +/- 1° ³
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 $^{^{\}star}$ Example drawing for general reference, please consult MVG-ORBIT/FR for ICD.

Supplied Accessories

Digital Documentation Set

User manual (installation, setup, operation & maintenance)

Technical Notes

1 Continuous roll also possible

2 Repeatability to zero

To reach the specified accuracy

