AZ/EL/AZ Positioners - Light Duty

AL-4555-1 • AL-4557-1 • AL-4580-1 • AL-4581-1

These 3-axis positioners provide accurate, balanced rotation, and controllable velocity in the positioning of light-duty antennas under test. Their compact and low-profile design optimizes space in test configurations as well as high operational performance, yielding the best size and weight/performance ratio.

Typically, the unit includes the body, precise bearings, DC motor, gear reducer, encoder and limit switch assemblies. The turntable surface is designed with a threaded mounting-hole pattern for ease of use.



Applications

- General purpose positioning subsystems
- Far-field & near-field antenna measurements
- Small antenna testing
- Indoor use

Product Highlights

- Compact, low profile design
- High angular positioning
- Adjustable travel in all axes
- Rotary joint 18/40 GHz (Optional)
- Upper AZ through hole (Optional)
- Vertical loads ranging from 13-600 lbs (6-270 kg)
- Turntable diameters ranging from 3.7-12.5 in (95-318 mm)
- Excellent angular position accuracy
- Low backlash design
- Precision bearings
- Closed loop servo control
- Industry-standard wiring
- Encoders for optimum speed regulation & control
- Fully enclosed design of drive gear train & data take-off



Specifications - Compact Series AZ/EL/AZ Light Duty Positioners

PARAMETER		UNITS	POSITIONER MODELS			
			AL-4555-1	AL-4557-1	AL-4580-1	AL-4581-1
Dimensional Drawing Number		DCD	220-1196	220-1207	212-0960	214-0630
OPERATIONAL						
Bending moment (max)		kg-m	2	10	35	80
		ft-lbs	14.5	72.3	250	580
Vertical load (max)		kg	6	25	60	273
		lbs	13.2	55.1	132	600
	Upper azimuth	kg-m	1	7	12	20
		ft-lbs	7.2	50.6	90	150
Delivered torque	Elevation	kg-m	1	7	38	60
Bonrorou torquo	Liovation	ft-lbs	7.2	50.6	273	435
	Lower azimuth	kg-m	1	7	12	20
	Lower azimuti	ft-lbs	7.2	50.6	90	150
	Upper azimuth	kg-m	3	10	20	30
		ft-lbs	21.7	72.3	150	210
		kg-m	3	10	58	80
Withstand torque	Elevation	ft-lbs	21.7	72.3	420	580
		kg-m	3	10	20	30
	Lower azimuth	ft-lbs	21.7	72.3	150	210
Drive power	Upper azimuth	hp	1/30	1/20	1/8	1/8
	Elevation	hp	1/30	1/20	1/8	1/4
	Lower azimuth	hp	1/30	1/20	1/8	1/8
	Upper azimuth	rpm	1	0.7	2.4	2.4
Nominal speed	Elevation	deg/min	360	250	360	360
	Lower azimuth	rpm	1	0.7	2.4	2.4
	Upper azimuth	deg	± 0.04	± 0.04	± 0.04 / ± 0.005	± 0.04 / ± 0.005
Position accuracy Std. encoder /	Elevation	deg	± 0.04	± 0.04	± 0.04 / ± 0.005	± 0.04 / ± 0.005
High accuracy encoder ^{1, 2}	Lower azimuth	deg	± 0.04	± 0.04	± 0.04 / ± 0.005	± 0.04 / ± 0.005
	Upper azimuth	deg	0.05	0.05	0.05	0.05
Maximum hacklash	Elevation	deg	0.05	0.05	0.05	0.05
Maximum backlash	Lower azimuth	deg	0.05	0.05	0.05	0.05
	Upper azimuth	deg	± 200	± 200	± 200	± 200
Travel ^{1, 2,3}	Elevation					
II avel '' -'-	Lower azimuth	deg	± 92 ± 200	± 92 ± 92	± 92 ± 200	± 92 ± 200
DUVELCAL	Lower azıllıdılı	deg	± 200	± 92	± 200	± 200
PHYSICAL		mana	317	475	674	715
Height at 0° elevation⁴		mm				
Weight		in	12.5	18.7	26.5	28.1
		kg	16	25	84	130
		lbs	35	55	185	286
Turntable diameter		mm	95	150	261	318
		in	3.7	5.9	10.3	12.5

ENVIRONMENTAL

	40 = 1					
Operating temperature	- 4° F to 140° F (- 20° C to 60° C)					
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PARAMETER UNITS POSITIONER MODELS

AL-4555-1 AL-4557-1 AL-4580-1 AL-4581-1

OPTIONS

	Incremental encoder (standard accuracy)		S	S	S	S
EN001	Accuracy – upper azimuth	deg	± 0.04	± 0.04	± 0.04	± 0.04
	Accuracy – elevation	deg	± 0.04	± 0.04	± 0.04	± 0.05
	Accuracy – lower azimuth	deg	± 0.04	± 0.04	± 0.04	± 0.04
EN004	Absolute encoder (standard accuracy)		Opt.	Opt.	Opt.	Opt.
	Accuracy – upper azimuth	deg	NA	± 0.04	± 0.04	± 0.04
	Accuracy – elevation	deg	NA	± 0.04	± 0.04	± 0.04
	Accuracy – lower azimuth	deg	NA	± 0.04	± 0.04	± 0.04
SR	Slip ring ³		-	-	SR051U SR101U SR201U	SR051U SR101U SR201U
RJ	Rotary joint ³		RJ18L RJ26L RJ40L RJ50L	RJ18L RJ26L RJ40L RJ50L	RJ18L RJ26L RJ40L RJ50L	RJ18L RJ26L RJ40L RJ50L
тн	Central thru-hole inner diameter		S	S	TH002 TH003	TH002 TH003
		in	0.75	1.6	1.5	2.5
		mm	20	40	38	63
EX	Internal harnessing		-	-	-	-
CF	Connector format		-	-	-	-
LS	Leveling screw (set)		-	-	-	-
ST	Stow lock		-	-	-	-
MM	Mounting thread (MM Std.)		-	-	MM002 MM003	MM002 MM003
IC	Interlock circuit		-	-	-	-

⁽⁻⁾ N/A S Standard Opt Optional

Supplied Accessories

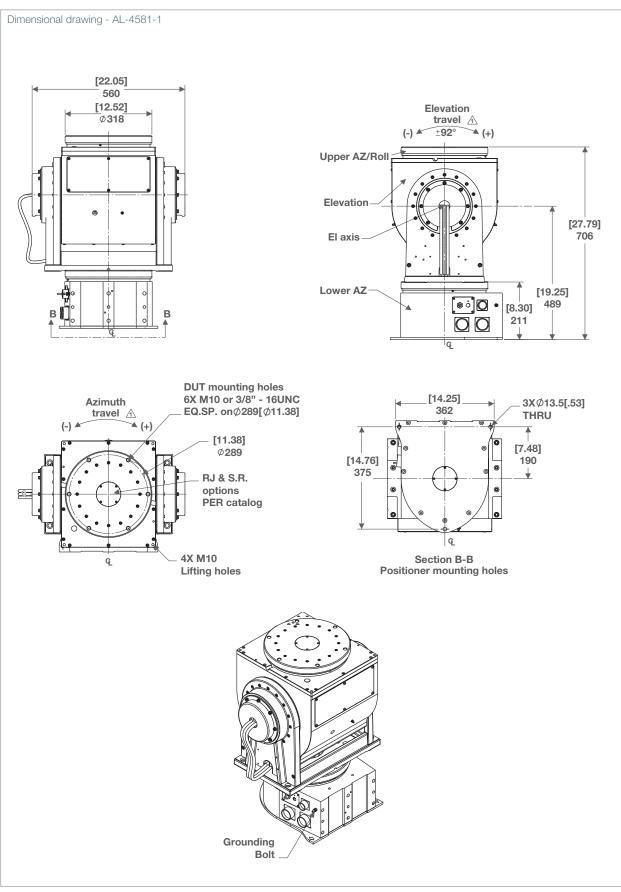
Digital Documentation Set

User manual (installation, setup, operation & maintenance)

Technical Notes

- With direct-drive encoder option implementation, the accuracy will be ± 0.005° and positioner dimensions might change slightly. (Only for AL-4580/1).
- Direct drive high accuracy options are not available for the small models, AL-4555-1 and AL-4557-1 due to size. For required enhanced accuracy contact factory.
- Pre-adjusted at factory to ± 200° or according to customer order specifications.
- 4 Height of positioner AL-4555-1 and AL-4557-1 can be reduced to approx. 60 mm when positioners are installed with cables hanging below
- # 5 All accuracy data is based on no-load conditions. Contact MVG-ORBIT/FR for accuracy under load conditions.

- 6 AL-4580-1 & AL-4581-1 are equipped with adjustable limit switches capable of approx. 20° to 400° total travel. When rotary joint and slip ring options are specified, limit switches remain but are electrically disabled.Multi-axis positioners are factory-set at:
 - Azimuth Axis: ± 200°
 - Elevation Axis: ± 92°
- AL-4555 & AL-4557 are equipped with adjustable limit for coarse adjustments only.
- 8 Slip ring & rotary joint option notes:
 - Certain slip ring options may require an extension cap that protrudes above the turntable surface. Positioner height may increase.
 Consult MVG-ORBIT/FR.
 - Slip ring contacts for customer use are provided with dedicated connectors.
 - When rotary joint and/or slip ring options are specified, no central thru-hole is available to the user. Option TH002 and TH003 are available in lieu of rotary joint and/or slip ring options.
- For slip ring option in AL-4555-1 and AL-4557-1 consult factory. Synchro and direct-drive encoders are not applicable for these models due to their compact size.
- **10** For outdoor applications, contact factory.



 $^{^{\}star}$ Example drawing for general reference, please consult MVG-ORBIT/FR for ICD.